# Math 141 - Matrix Algebra for Engineers 

G.Pugh

Jan 72015

## Systems of Linear Equations

## Goal

We wish to solve systems of linear equations, for example

$$
\begin{aligned}
4 x+3 y-6 z & =-2 \\
-x+y+z & =2 \\
x-2 y-z & =-3
\end{aligned}
$$

That is, we wish to find all $(x, y, z)$ which satisfy all equations simultaneously.

First, some terminology and notation...

## Linear Equations

A linear equation in $n$-variables $x_{1}, x_{2}, \ldots, x_{n}$ is an equation of the form

$$
a_{1} x_{1}+a_{2} x_{2}+\cdots+a_{n} x_{n}=b
$$

where $a_{1}, a_{2}, \ldots, a_{n}$ and $b$ are real numbers.

Example: $2 x+4 y-z=5$ is a linear equation in 3 -variables.

If $b=0$, say the equation is homogeneous.

Example: $7 x_{1}+3 x_{2}-4 x_{3}+11 x_{4}=0$ is a homogeneous linear equation in 4 -variables.

## What Makes a Linear Equation Linear

Important: in a linear equation, each term involving the variable is of form
(real number)(variable raised to power 1)

There are no terms of form
$\sin x, \cos y, \ln x, e^{x}, x y, 1 / x, x^{2}, \sqrt{1+x}$, etc

## Systems of Linear Equations

A system of linear equations is a finite collection of linear equations:

Example: A system of 2 equations in 3 variables, or 3 unknowns:

$$
\begin{aligned}
4 x+3 y-6 z & =-2 \\
-x+y+z & =2
\end{aligned}
$$

## A General System

A general system of $m$ equations in $n$ unknowns:

$$
\begin{gathered}
a_{11} x_{1}+a_{12} x_{2}+\cdots+a_{1 n} x_{n}=b_{1} \\
a_{21} x_{1}+a_{22} x_{2}+\cdots+a_{2 n} x_{n}=b_{2} \\
\vdots \quad \vdots \\
a_{m 1} x_{1}+a_{m 2} x_{2}+\cdots+a_{m n} x_{n}=b_{m}
\end{gathered}
$$

A solution to this system is a set of numbers $x_{1}=p_{1}, x_{2}=p_{2}, \ldots, x_{n}=p_{n}$ which make all equations of the system true simultaneously.

Sometimes solutions are stated in vector form $\left(p_{1}, p_{2}, \ldots, p_{n}\right)$, also called an ordered $n$-tuple.

## Consistent Systems of Equations

A system of linear equations is called consistent if it has at least one solution, otherwise it is called inconsistent.

Example: We saw that

$$
\begin{aligned}
2 x+3 y & =-4 \\
-3 x+y & =-5
\end{aligned}
$$

had solution $(1,-2)$, so the system is consistent.

Geometrically this says that the two lines intersect at the point $(1,-2)$.

## Two Equations in Two Unknowns

A linear equation in 2-variables represents a line in 2-dimensions.

Two equations in two unknowns corresponds to lines that are either parallel, intersecting, or coincident:


No solution


One solution


```
Infinitely many
    solutions
(coincident lines)
```


## Linear Equations in Three Variables

To graph an equation in 3-variables requires the three dimensional rectangular coordinate system:


## Planes in 3-Dimensions

The graph (set of all points satisfying the equation) of a linear equation in 3 -variables is a plane, an infinite flat sheet.

Example: Graph the plane $x+2 y+3 z=6$

## Three Equations in Three Unknowns

The solution of a system of three equations in three unknowns describes how the three planes intersect in three dimensions:


No solutions
(three parallel planes; no common intersection)


One solution
(intersection is a point)


No solutions (two parallel planes; no common intersection)


No solutions (no common intersection)


No solutions (two coincident planes parallel to the third; no common intersection)


Infinitely many solutions (two coincident planes; intersection is a line)

## Important Observation

Notice that in the case of linear systems in two or three variables, the systems have either zero, exactly one, or infinitely many solutions. This turns out to be true for any system of linear equations.

## Representing Infinitely Many Solutions

## Example: Solve the system

$$
\begin{aligned}
x-2 y & =4 \\
-\frac{1}{4} x+\frac{1}{2} y & =-1
\end{aligned}
$$

Solution: (one way, to illustrate a point) Multiply the second equation by 4 :

$$
\begin{aligned}
x-2 y & =4 \\
-x+2 y & =-4
\end{aligned}
$$

Now add the first equation to the second:

$$
\begin{aligned}
x-2 y & =4 \\
0 & =0
\end{aligned}
$$

## Representing Infinitely Many Solutions

This says that any $(x, y)$ which satisfies $x-2 y=4$ is a solution to the system. There are infinitely many such pairs which we represent in parametric form:

Since $x-2 y=4, \quad x=4+2 y$.

Let $y=t$, so $x=4+2 t$.

So the solution to the system is $(4+2 t, t)$ where $t$ is any real number.

## Parametric Representation of Solutions

In the solution $(4+2 t, t)$ the variable $t$ is called a parameter. Letting the parameter vary over all real numbers produces all possible solutions.

For example, letting $t=0$ gives the solution $(4,0)$.

Letting $t=-3$ gives another solution $(-2,-3)$.

Letting $t=\pi$ gives $(4+2 \pi, \pi)$, etc.

## Another Example: Infinitely Many Solutions

Example: Solve the system

$$
3 x+2 y-z=3
$$

Solution: This time, any $(x, y, z)$ which satisfies the single equation is a solution. Once any two of the variables are specified, the third is determined, so two parameters are needed to represent the solution set.
Write $x=1-\frac{2}{3} y+\frac{1}{3} z$.
Let $y=r, z=t$, so that $x=1-\frac{2}{3} r+\frac{1}{3} t$.
The solution is then $\left(1-\frac{2}{3} r+\frac{1}{3} t, r, t\right)$ where $r$ and $t$ are any real numbers.

