

FRST121 – Mapping and Photogrammetry

Fall 2010

Practical Navigation Tools



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Outline

- ▶ Resection, intersection and triangulation
- ▶ Navigating with the N star
- ▶ Finding N-S with the sun

Where am I?

Resection

- ▶ Finding your position by getting a compass bearing to 2 or 3 known points on a map
- ▶ You are AT the unknown point



Where is that?

Intersection

- ▶ Locating a feature or object by getting a compass bearing from 2 or 3 known points
- ▶ You are AWAY from the unknown point

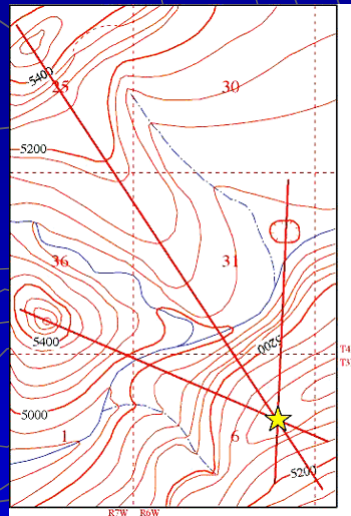
Triangulation

- ▶ Locating a point by measuring angles from two known points along a fixed baseline
- ▶ Same basic idea

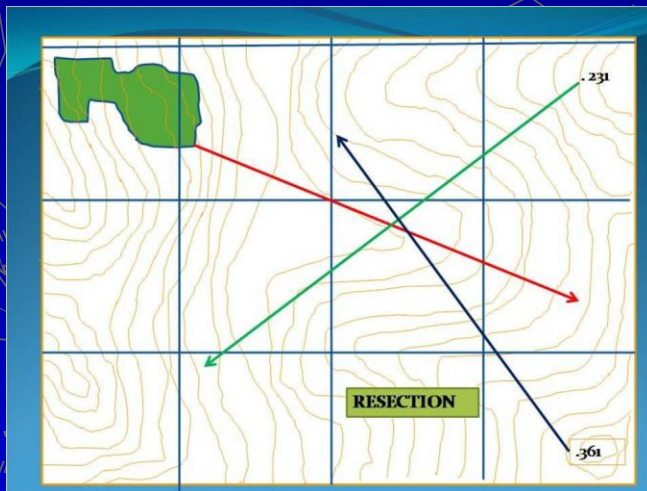


Determining your location (resection)

- ▶ Find 3 features that you can pinpoint on your map
- ▶ Mountain tops, junctions (rivers, roads)
- ▶ Take azimuth and plot the reverse (180°) with a line



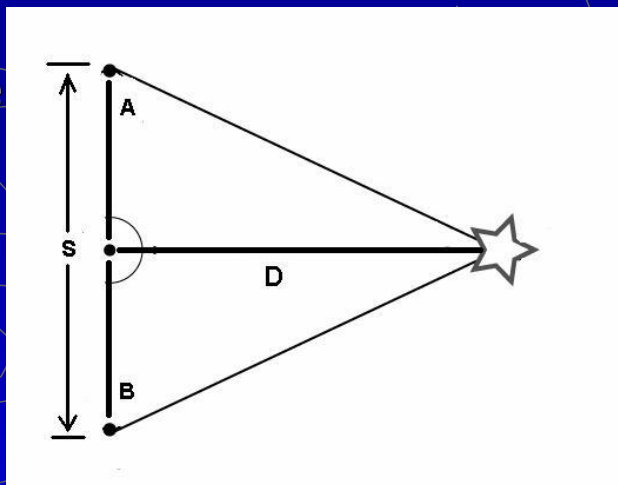
What if it's not perfect?



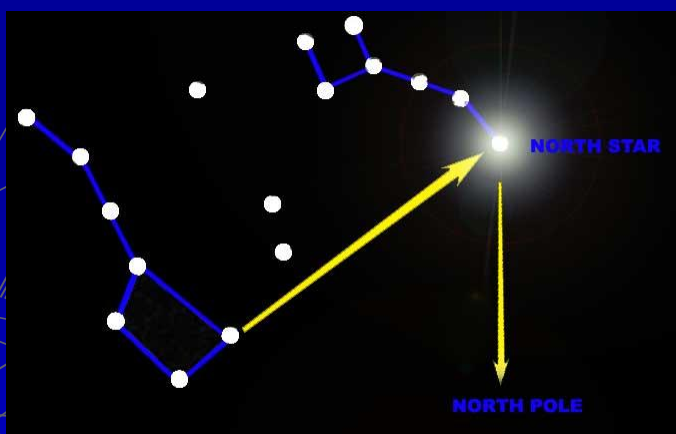
- ▶ You'll be within the "triangle of error"
- ▶ Re-do if it is too big

Triangulation

- ▶ Measure a baseline
- ▶ Measure angles A and B
- ▶ You can also get a distance (D)

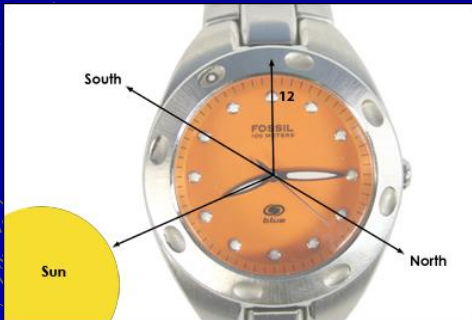


Using Polaris



- N star is always within 2 degrees of true north
- The vertical angle from the horizon = latitude

Using the sun and a watch



- ▶ The sun is due S at noon (Std. Time)
- ▶ Due E at 6 a.m.
- ▶ Due W at 6 p.m.
- ▶ At other times...
 - point hour hand at the sun
 - S is half way to 12

That's it...so get lost!

